# Advanced Methods in Natural Language Processing

Session 2: Neural Networks, Backpropagation & Recurrent Neural Networks

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Barcelona School of Economics

# Introduction

# Today's Focus: Understanding the Core of Neural Networks

- Neural Networks Basics: Exploring the structure and function of simple neural networks.
- Gradient Descent and Backpropagation: Unveiling how neural networks learn and optimize.

#### Advancing to Complex Models

- Recurrent Neural Networks (RNNs): Delving into the handling of sequential data.
- Long Short-Term Memory (LSTM) Networks: Understanding how LSTMs tackle the limitations of traditional RNNs.
- Language Models: Introducing and exploring basic language models.

# **Neural Networks**

#### Introduction to Neural Networks

- Diverse Network Types: Neural Networks encompass various architectures, each suited to specific tasks.
  - Multi-layer Perceptrons (MLPs): Basic form of NNs.
  - Recurrent Neural Networks (RNNs): Ideal for sequential data like text (Rumelhart et al., 1986).
  - Convolutional Neural Networks (CNNs): Specialized in processing structured grid data like images (LeCun et al., 1989).
  - *Transformers*: NLP Revolution with attention mechanisms (Vaswani et al., 2017).
- Understanding the Basics: Before delving into complex models, it's crucial to grasp the foundational principles.
  - Avoiding the "black box" approach
  - Blind feature engineering without algorithmic understanding.
- Vanilla Neural Networks: Also known as single-layer backpropagation networks, these form the cornerstone of more complex architectures.

• **K-Class Classification**: With K targets  $Y_k, k \in [1, K]$ .

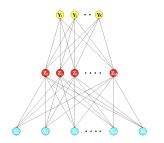


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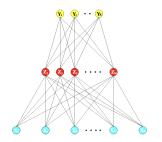


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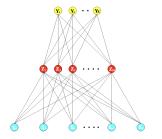


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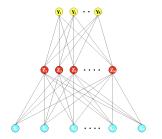


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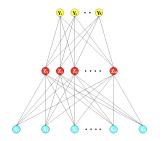


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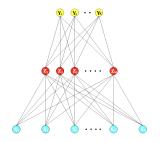


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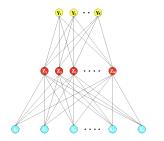


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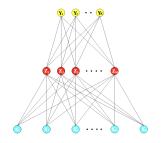


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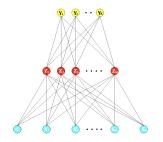


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# Vanilla Neural Networks: The Role of Non-Linearity

- Identity Function σ(v) = v: Reduces to a linear model; typically used in output layers for regression.
- Rectified Linear Unit (ReLU)
   σ(v) = max(0, v): Popular for deep
   networks.
- Sigmoid Function σ(v) = 1/(1+e^{-v}):
   Commonly used, depicted on the right.
- Hyperbolic Tangent σ(v) = tanh(v): Similar to sigmoid but ranges from -1 to 1.
- Others: Various options available in deep learning libraries like Keras.

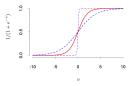


FIGURE 11.3. Plot of the sigmaid function  $\sigma(v) = 1/(1+exp(-v))$  (red curve), commonly used in the hidden layer of a neural network. Included are  $\sigma(sv)$  for  $s = \frac{1}{3}$  (blue curve) and s = 10 (purple curve). The scale parameter s controls the activation rate, and we can see that large s amounts to a hard activation at v = 0. Note that  $\sigma(s(v - v_0))$  shifts the activation threshold from 0 to  $v_0$ .

## Fitting the Vanilla Neural Network - Classification Problem

- Hidden Layer ( $\forall m \text{ in } [1, M]$ ):  $Z_m = \sigma(\alpha_{0m} + \alpha_m^T X)$
- Output Layer ( $\forall k \text{ in } [1, K]$ ):  $T_k = \beta_{0k} + \beta_k^T Z$
- Softmax Output ( $\forall k \text{ in } [1, K]$ ):  $Y_{k} = \frac{e^{T_{k}}}{e^{T_{k}}} = f_{k}(X)$

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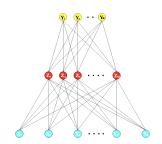


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**Dimensionality and Loss Function** 

• 
$$\alpha_{0m} \in \mathbb{R}^{M}, \ \alpha_m \in \mathbb{R}^{M \times p}, \ \beta_{0k} \in \mathbb{R}^{K}, \ \beta_k \in \mathbb{R}^{M \times K}.$$

- Total Weights to Optimize (θ):
   M(p+1) + K(M+1).
- $L(\theta) = -\sum_{k=1}^{K} y_k \log(f_k(x))$
- $L(\theta) = -\sum_{i=1}^{N} \sum_{k=1}^{K} y_{ik} \log(f_k(x_i))$

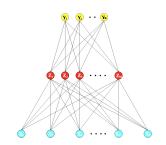


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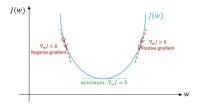
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  - *Mini-batch Gradient Descent*: Strikes a balance using subsets of the dataset.

#### Update Rule:

$$\theta = \theta - \eta \nabla_{\theta} L(\theta)$$

with  $\eta$  as the **learning rate**.



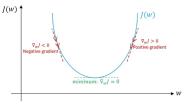
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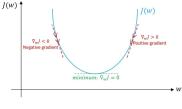
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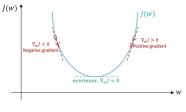
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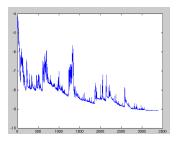
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**Limitation**: Requires processing **the entire dataset** for each update, problematic for large datasets due to memory constraints.



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Update for Each Observation: Applies the gradient descent update rule for each observation individually, chosen randomly.

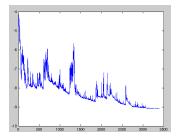


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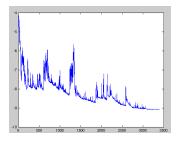
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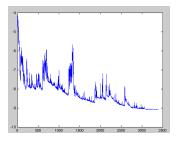
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**Challenge**: Tendency to oscillate around or even overshoot minima. Reducing  $\eta$  over time can mitigate this issue.



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#### **Mini-batch Gradient Descent**

Combining the Best of Both Worlds! Update Rule:

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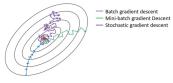
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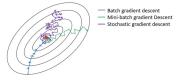
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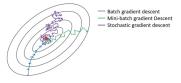
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**Widely Adopted**: Often the preferred choice in practical applications and deep learning frameworks.



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- Issue: Getting trapped in local minima.

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- Understanding the Chain Rule:

$$\frac{\partial f(x)}{\partial z} = \frac{\partial f(x)}{\partial t} \frac{\partial t}{\partial z}$$

Key to computing gradients for backpropagation.

#### **Classification Problem Formulation:**

• For each hidden unit *m* in [1, *M*]:  $Z_m = \sigma(\alpha_{0m} + \alpha_m^T X)$ 

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## Application to a Single-Layer Neural Network

- For each hidden unit *m* in [1, *M*]:  $Z_m = \sigma(\alpha_{0m} + \alpha_m^T X)$
- For each output unit k in [1, K]:  $T_k = \beta_{0k} + \beta_k^T Z$

• For the softmax output: 
$$Y_k = \frac{e^{T_k}}{\sum_{l=1}^{K} e^{T_l}} = g_k(T) = f_k(X)$$

## Application to a Single-Layer Neural Network

- For each hidden unit *m* in [1, *M*]:  $Z_m = \sigma(\alpha_{0m} + \alpha_m^T X)$
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#### **Classification Problem Formulation:**

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#### Applying the Chain Rule to Compute Gradients for $\beta_k$ :

Gradient of the loss function with respect to β<sub>k</sub>:

$$\frac{\partial L(\theta)}{\partial \beta_k} = -\frac{\partial}{\partial \beta_k} \sum_{j=1}^K \sum_{i=1}^N y_{ij} \log(f_j(x_i))$$

Derivatives of  $\beta_k$  - Part 1

$$\begin{aligned} \frac{\partial L(\theta)}{\partial \beta_k} &= -\sum_{j=1}^{K} Y_j \frac{\partial \log(\hat{Y}_j)}{\partial \beta_k} \\ &= -\sum_{j=1}^{K} Y_j \left( \frac{\partial T_j}{\partial \beta_k} - \frac{\partial \log(\sum_{l=1}^{K} e^{T_l})}{\partial \beta_k} \right) \\ &= -\sum_{j=1}^{K} Y_j \left( \mathbf{1}_{j=k} Z^T - \frac{e^{T_k} Z^T}{\sum_{l=1}^{K} e^{T_l}} \right) \\ &= -\sum_{j=1}^{K} Y_j \left( \mathbf{1}_{j=k} Z^T - \hat{Y}_k Z^T \right) \end{aligned}$$

14

Derivatives of  $\beta_k$  - Part 2

$$\frac{\partial L(\theta)}{\partial \beta_k} = -\sum_{j=1}^K Y_j \left( \mathbf{1}_{j=k} Z^T - \hat{Y}_k Z^T \right)$$
$$= \left( \sum_{j=1}^K Y_j \hat{Y}_k - \sum_{j=1}^K Y_j \mathbf{1}_{j=k} \right) Z^T$$
$$= \left( \hat{Y}_k \sum_{j=1}^K Y_j - Y_k \right) Z^T$$
$$= \left( \hat{Y}_k - Y_k \right) Z^T$$
$$\beta_k^{r+1} = \beta_k^r - \eta \frac{\partial L(\theta)}{\partial \beta_k}$$
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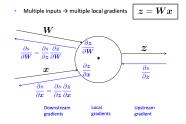
## Backpropagation: Understanding the Chain Rule

#### The Chain Rule in Neural Networks:

• Fundamental to backpropagation:

$$\frac{\partial f(x)}{\partial z} = \frac{\partial f(x)}{\partial s} \frac{\partial s}{\partial z}$$

- downstream gradient = upstream gradient × local gradient.
- This principle encounters challenges:
  - Vanishing Gradient: Gradients become very small, hindering learning.
  - *Exploding Gradient*: Gradients grow too large, leading to unstable learning.
- It can prevent the model from learning!



Credit: Christopher Manning

## **Understanding Vanishing Gradient**

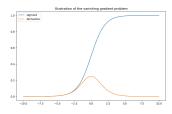
- When gradients become increasingly small as they are propagated back through the layers.
- Especially in networks with many layers.

#### Illustrative Example:

- Consider a deep NN with sigmoid.
- Sigmoid gradients in (0, 0.25].
- Multiplying many such small values (chain rule!) makes the gradient increasingly smaller.

#### **Consequence:**

 Lower layers of the network learn very slowly, making training ineffective.



Sigmoid and its derivative

## **Understanding Exploding Gradient**

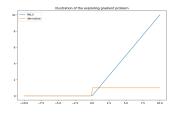
- When gradients become excessively large: model weights oscillate wildly.
- Often seen in NN with improper initialization or high learning rates.

#### Illustrative Example:

- NN with large weight values and high learning rates.
- Small changes in input lead to large changes in the output.
- Gradients can grow exponentially during backpropagation through layers.

#### Consequence:

 Results in unstable training: weights diverge and NN fail to converge.



ReLU and its derivative

# **Complex Models**

## **Recurrent Neural Networks**

## **Overview of RNNs:**

- RNNs, introduced by Rumelhart et al. (1986), are powerful networks for sequential data processing.
- Key Models: Vanilla RNNs and Long Short-Term Memory (LSTM) networks.
- State-of-the-art in various NLP tasks (e.g., machine translation, text generation) before the advent of Transformers and BERT models.

## Motivation for Using RNNs:

- Sequential Data Processing:
  - Traditional feed-forward networks are not optimized for sequential data like text or time series.
  - RNNs are designed to handle data where variables are interlinked sequentially.

#### Example - Text Analysis:

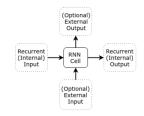
- For a word like "mathematics," tokenized as "m, a, t, h, e, m, a, t, i, c, s," RNNs can capture the sequence's inherent dependencies.
- This sequential understanding is crucial for tasks like language modeling and translation.

# Recurrent Neural Networks -General

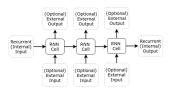
### What is a Recurrent Neural Network?

#### Characteristics of RNNs:

 Composed of identical units resembling feed-forward neural networks.



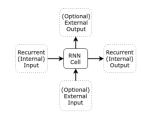
Single RNN Cell



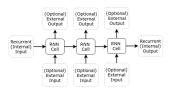
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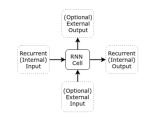
- Composed of identical units resembling feed-forward neural networks.
- Inputs for Each Cell:



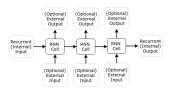
#### Single RNN Cell



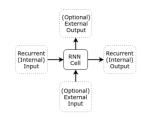
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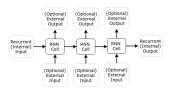
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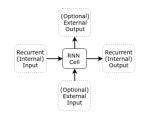
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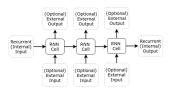
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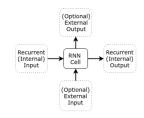
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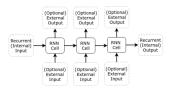
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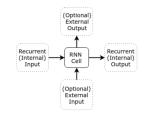
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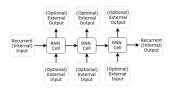
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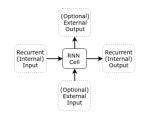
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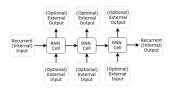
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- Outputs for Each Cell:
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  - Internal Output: The state passed to the next cell.
- Functions by passing states from one cell to the next in a sequence.



### Single RNN Cell

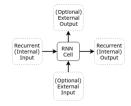


#### Mathematical Formulation:

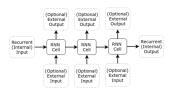
$$\begin{pmatrix} s_t \\ o_t \end{pmatrix} = f\left( \begin{pmatrix} s_{t-1} \\ x_t \end{pmatrix} \right)$$

#### Where:

 s<sub>t</sub> and s<sub>t-1</sub> are the current and previous states, respectively.



### Single RNN Cell



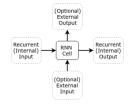
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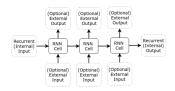
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- $o_t$  is the output at time t.





### Single RNN Cell

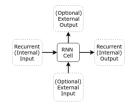


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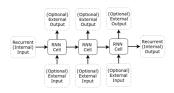
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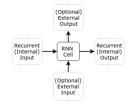


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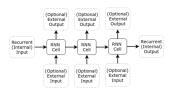
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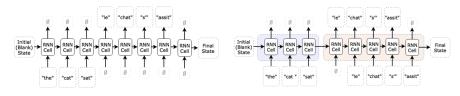
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- $o_t$  is the output at time t.
- *x<sub>t</sub>* is the current input (optional).
- *f* represents the recurrent function, defining how the next state and output are computed.



### Single RNN Cell



- RNNs are particularly effective in sequence-to-sequence tasks like language translation.
- They process sequential inputs and generate sequential outputs, capturing the nuances of language patterns.



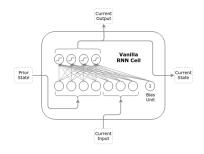
RNN for Translation - Example 1 RNN for Translation - Example 2 Credit: R2Rt blog

# Vanilla Recurrent Neural Network

#### Characteristics of the Vanilla RNN:

• Features a single layer with identical current output and current state.

Mathematical Description:

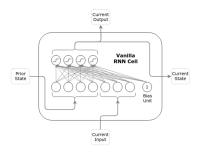


The Vanilla RNN.

#### Characteristics of the Vanilla RNN:

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Mathematical Description:



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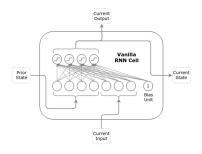
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#### Mathematical Description:

State Update:

 $s_t = \phi(Ws_{t-1} + Ux_t + b)$ 



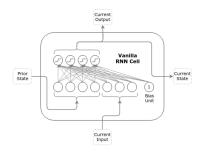
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- Activation Function:  $\phi$



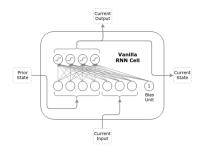
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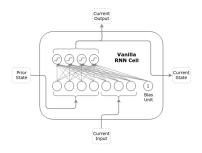
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- Weights:  $W \in \mathbb{R}^{n \times n}$ ,  $U \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^n$





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- Challenge in learning long-term dependencies.
- Mitigation strategies: regularization and specific weight initialization (Pascanu et al., 2013; Xavier-Glorot, Glorot and Bengio, 2010).

# Long Short Term Memory

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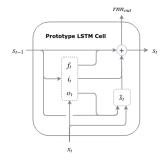
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    - Forget Gate: Decides which parts of the memory may no longer be relevant.

#### LSTM Gate Functions:

Write Gate (*i<sub>t</sub>*): Determines new information to be stored in the cell state. *i<sub>t</sub>* = σ(W<sub>i</sub>s<sub>t-1</sub> + U<sub>i</sub>x<sub>t</sub> + b<sub>i</sub>)

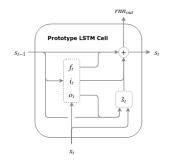


figurePrototype LSTM Cell. Credit: R2Rt blog

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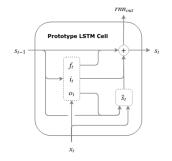
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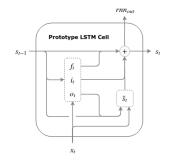
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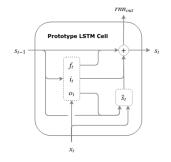


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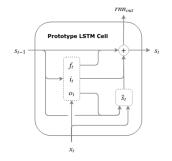
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Final cell state:

$$s_t = f_t \odot s_{t-1} + i_t \odot \tilde{s}_t$$



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## State-of-the-Art Applications of LSTM (or extentions)

#### 1. Sentiment Analysis:

- LSTM networks, often in combination with word embeddings, have set new benchmarks in sentiment analysis tasks.
- SST-2 dataset (Radford et al., 2017), IMDb (Gray et al., 2017)
- 2. Machine Translation (MT):
  - LSTM-based models were pivotal in advancing the performance of neural machine translation systems.
  - English German (Luong et al., 2015), English-French (Cho et al., 2014)

#### 3. Language Modelling:

- LSTMs have been successfully applied in language modelling, reducing text perplexity substantially.
- WikiText-103 dataset (Rae et al., 2018), TreeBank dataset (Aharoni et al., 2015)

#### Generating a Classificaiton model with LSTM architecture

Using Python's keras library to apply a LSTM-based model.

#### Python Code, source: Keras

```
import numpy as np
import keras
from keras import layers
max_features = 20000  # Only consider the top 20k words
maxlen = 200  # Only consider the first 200 words of each movie review
```

## LSTM for IMDb classification (2/3)

```
# Input for variable-length sequences of integers
inputs = keras.Input(shape=(None,), dtype="int32")
# Embed each integer in a 128-dimensional vector
x = layers.Embedding(max_features, 128)(inputs)
# Add 2 bidirectional LSTMs
x = layers.Bidirectional(layers.LSTM(64, return_sequences=True))(x)
x = layers.Bidirectional(layers.LSTM(64))(x)
# Add a classifier
outputs = layers.Dense(1, activation="sigmoid")(x)
model = keras.Model(inputs, outputs)
model.summary()
```

Model: "functional\_1"

Layer (type)	Output Shape	Param #
<pre>input_layer (InputLayer)</pre>	(None, None)	0
embedding (Embedding)	(None, None, 128)	2,560,000
bidirectional (Bidirectional)	(None, None, 128)	98,816
bidirectional_1 (Bidirectional)	(None, 128)	98,816
dense (Dense)	(None, 1)	129

## LSTM for IMDb classification (3/3)

#### Python Code to train, source: Keras

```
(x_train, y_train), (x_val, y_val) = keras.datasets.imdb.load_data(
num words=max features
# Use pad sequence to standardize sequence length:
# this will truncate sequences longer than 200 words
# and zero-pad sequences shorter than 200 words.
x_train = keras.utils.pad_sequences(x_train, maxlen=maxlen)
x val = keras.utils.pad sequences(x val, maxlen=maxlen)
model.compile(optimizer="adam", loss="binary crossentropy",
              metrics=["accuracv"])
model.fit(x train, y train, batch size=32, epochs=2,
          validation_data=(x_val, y_val))
```

 Epoch 1/2

 782/782

 Epoch 2/2

 782/782

 54s 69ms/step - accuracy: 0.7540 - loss: 0.4697 - val\_accu

 782/782

<keras.src.callbacks.history.History at 0x7f3efd663850>

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  - *LSTM with Peepholes* (Graves, 2013): Incorporates peephole connections to enhance the model's memory capability.

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Formal Definition:

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## Importance of Language Modeling:

• Enables NLP systems in generating human-like language.

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- Used to train BERT and GPT-like models.

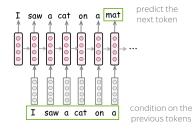
## Language Model as Next Token Prediction

#### Next Token Prediction:

- $P(w_{1:n}) = \prod_{i=1}^{n} P(w_i | w_1, w_2, ..., w_{i-1})$
- Focus on Next Token Prediction,
   P(w<sub>i</sub>|w<sub>1</sub>, w<sub>2</sub>, ..., w<sub>i-1</sub>): predict the next word given previous ones.

### With RNNs:

- Input: Sequence of tokens. "I saw a cart on a", the model receives "I", "saw", "a", "cat", "on", "a" as input one after the other.
- **Output**: At each step, the RNN predicts the probability distribution of the next token. Here "mat"



Credit: Lena Voita

## Next Token Prediction with top-5 proposition when training a model:

	Е	n	g	L.	i.	s	h	-	L	а	n	g	u	а	g	е		w	e	ь	s	i.	t	е		o	f
	х	g	I.	i.	s	h		I.	i	n	g	u	а	g	e	s	а	i	r	s	i.	t	е		0	f	
k	n	t	i.	а	с	а	-	s	а	r	d	e	e	L	h		0	а	n		t	b	i.	s	а	n	f
	d	С	е	е	n		е	р	е	s	а	а	i	k	i		i.	е	е	L	е	d	h		i.	r	t
•	v	d	r	у	z	i.		С	0	u	е	d	I.	s	u	:	t	h	а	-	0	0			t	u	,
	L	٧	а	0	d			е	у	t	с	-	n		d	m	-	0	i.	b	u	٧	s	]	b	b	

Credit: Karpathy

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#### Limitations of One-Hot Representations:

- **Sparsity**: One-hot vectors are sparse and do not capture any semantic/contextual information.
- **Dimensionality**: The dimension of one-hot vectors grows with the size of the vocabulary, leading to scalability issues.

#### Transition to Dense Word Embeddings:

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**Upcoming Session:** We will delve deeper into the world of word embeddings, exploring how they revolutionize the understanding and representation of words in NLP models.

#### **Open Discussion**

- Feel free to ask questions or share your thoughts about today's topics.
- Any insights, experiences, or perspectives you'd like to discuss are welcome.

## Summary of Key Takeaways

- Neural Networks: Explored the fundamentals of Neural Networks, including Vanilla Networks, Backpropagation, and Gradient Descent.
- **Gradient issues**: Illustrated the the issues of vanishing and exploding gradients and gave some paths to avoid it.
- RNNs: Discussed the significance of RNNs in handling sequential data and their applications in tasks like language modeling and machine translation.
- **LSTM:** Introduced the concept of gates (Write, Read, Forget) to control the flow of information.
- Language Modeling: Introduced it with RNNs: how are used for language modeling, emphasizing their ability to capture long-term dependencies.